



UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										CONDUIT BOX							
	A	B	C	D	G	J	K	M	O	P	T	MAXIMUM KEY SEAT	AB	AC	AE	AF	XL	XN
5010USS	24.8	39.8	64.9	12.50	2.6	6.3	6.7	24.8	26.2	29.5	5.1	4.00	24.8	20.4	12.5	9.2	15.2	10.2
5010US	24.8	39.8	66.3	12.50	2.6	6.3	6.7	24.8	26.2	29.5	5.1	4.00	24.8	20.4	12.5	9.2	15.2	10.2
5010UZ	24.8	39.8	71.7	12.50	2.6	6.3	6.7	24.8	26.2	29.5	5.1	4.00	24.8	20.4	12.5	9.2	15.2	10.2

FRAME SIZE	MOUNTING				SHAFT EXTENSION				KEY SEAT				BEARINGS		MAXIMUM WEIGHT
	E	ZF	H	BA	N-W	V	U	R	S	ES	LS	OS			
5010USS	10.00	32.00	1.2	8.50	4.75	4.50	2.375	2.021	0.625	3.00	6313C3	NU313C3			
5010US	10.00	32.00	1.2	8.50	6.25	6.19	3.625	3.134	0.875	5.00	6320C3	6320C3			
5010UZ	10.00	32.00	1.2	8.50	11.62	11.38	4.375	3.817	1.000	10.00	NU324C3	6320C3			

TAG NO's: . . . . .

CUSTOMER: \_\_\_\_\_ MOTOR MODEL NO.: \_\_\_\_\_  
 P.O. NO.: \_\_\_\_\_ HP: \_\_\_\_\_ VOLTAGE: \_\_\_\_\_ RPM(SYN): \_\_\_\_\_ HZ: \_\_\_\_\_  
 FRAME SIZE: \_\_\_\_\_ PRODUCT TYPE: IEF3 EQP III 840 & 841  
 COMMENTS: \_\_\_\_\_  
 \_\_\_\_\_  
 \_\_\_\_\_  
 PER: \_\_\_\_\_ DATE: \_\_\_\_\_

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 DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED  CERTIFIED

- STANDARD (NO AUX. BOXES)
- RTD AUX. BOX
- SPACE HEATER AUX. BOX
- BEARING RTD's

- NOTES:
- DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT
  - MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS
  - KEY DIMENSIONS EQUAL S x S x 10.00 FOR UZ, S x S x 5.00 FOR US, AND S x S x 3.00 FOR USS
  - MOTOR WEIGHT SHOWN IS MAXIMUM (MOTOR SUPPLIED WITH KEY)
  - MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME
  - STANDARD 4-8 POLE PRODUCT USES BI-DIRECTIONAL FAN. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE
  - STANDARD 2 POLE PRODUCT USES UNI-DIRECTIONAL FAN. OPPOSITE ROTATION AVAILABLE ONLY BY FAN AND CONNECTION CHANGE

**TOSHIBA**  
 TOSHIBA INTERNATIONAL CORPORATION

TOTALLY-ENCLOSED FAN-COOLED  
 HORIZONTAL FOOT-MOUNTED  
 3 PHASE INDUCTION MOTOR  
 F1 ASSEMBLY

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**TYPICAL MOTOR PERFORMANCE DATA**

Model: F5006FLF4BMHD

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
500	373	6	1190	5810UZ	460	60	3	591.10
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	54	F	1.15	CONT	95.4	-	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	500	372.9	591.1	95.7	82.8
¾ Load	375.00	279.6	455.6	95.4	80.8
½ Load	250.00	186.4	332.4	94.5	74.5
¼ Load	125.00	93.2	205.2	91.4	62.4
No Load			190.3		3.2
Locked Rotor			3572.3		25.9

Torque				Rotor wk <sup>2</sup> Inertia (lb-ft <sup>2</sup> )
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
2207	160	125	210	413.91

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
34	12	-	6320C3	6320C3	

\*Bearings are the only recommended spare part(s).

**Motor Options:**  
Product Family:EQP Global 840  
Mounting:Footed,Shaft:UZ Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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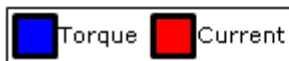
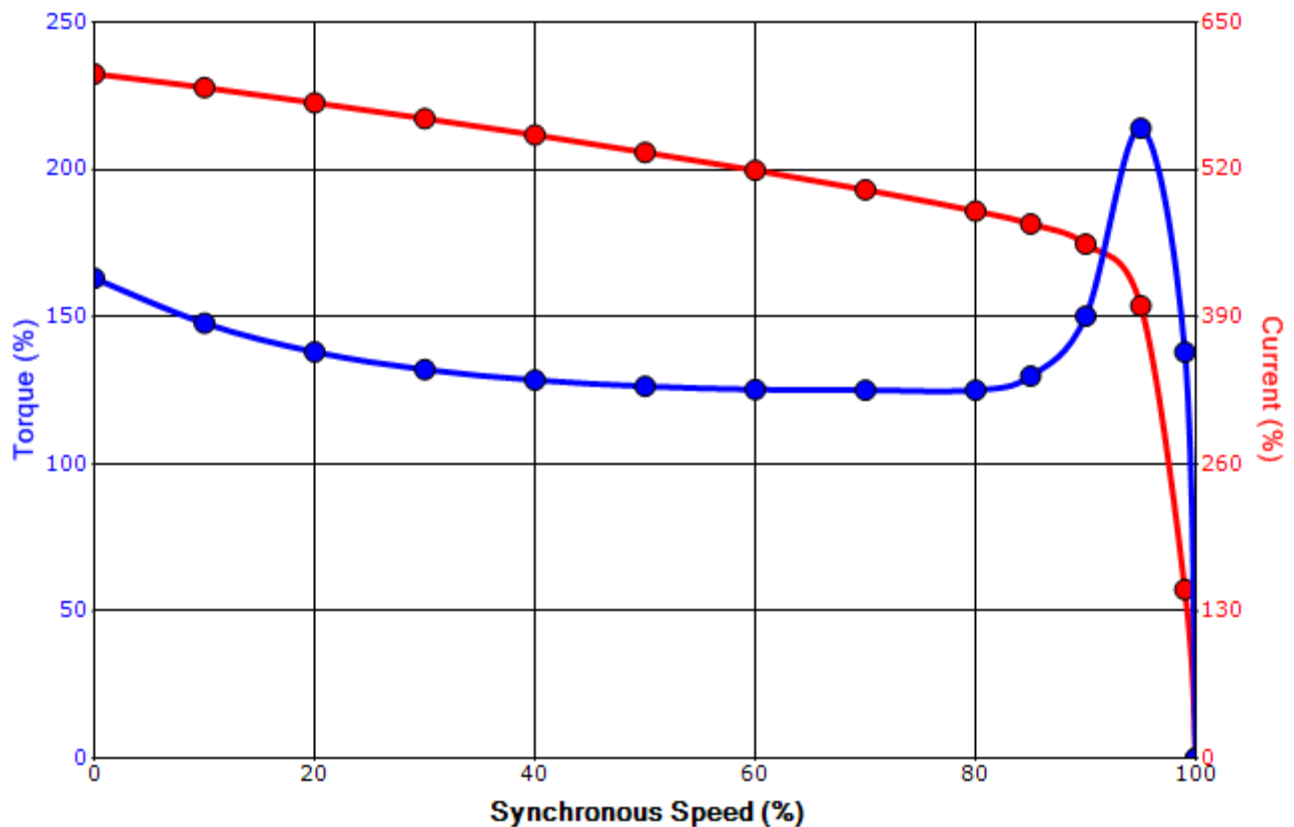
Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	4/30/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

**SPEED TORQUE/CURRENT CURVE**

Model: F5006FLF4BMHD

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
500	373	6	1190	5810UZ	460	60	3	591.10
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	54	F	1.15	CONT	95.4	-	G	40 C
Locked Rotor Amps	Rotor wk <sup>2</sup> Inertia (lb-ft <sup>2</sup> )	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
3572.3	413.91	2207	160	125			210	

**Design Values**



Customer		wk <sup>2</sup> Load Inertia (lb-ft <sup>2</sup> )	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

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Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	4/30/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

### Motor Connection Diagram 3 Leads - Delta Connection



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.  
If multiple cables represent a single lead, each one  
of them will be labeled with the appropriate lead number.